Lecture Series – 9 Solving Differential equations using SIMULINK



Shameer Koya

Solve the differential equation

$$\frac{dx}{dt} = -2x + 1, \quad t > 0.$$
$$x(0) = 0.$$

- Note: The input is 1 after t> 0
- Input step function stepping time is not t=1 but t=0
- Initial Condition is o



- The equation is Dx = -2x + 1 where $D = \frac{d}{dt}$
- Instead of differentiation, we do the reverse operation, integration, to solve the equations
- In SIMULINK $\frac{1}{s}$ means integration
- Input to the integrator is $Dx = \frac{dx}{dt}$ and output x
- set up the right hand side and connect the everything to the input of the integrator.



- Another issue that we have not considered is initial condition.
- As you know every differential equation should have initial conditions given.
- The default value in SIMULINK is zero.
- To change that click the integrator.



• If you want to see both the input and output at the same time, use *Mux* (multiplexer) block, which you can find under *Signals and Systems*

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Higher order differential equation

Second order equation

$$\frac{d^2x}{dt^2} = -5\frac{dx}{dt} - 9x$$

 $\frac{dx}{dt} = \dot{x}(0) = -2$ x(0) = 2

- To set up the right-hand side two integrators are needed
- The input to the first integrator is the second derivative $\frac{d^2x}{dt^2}$ and its output is $\frac{dx}{dt}$
- second integrator producing x(t) at its output

• Assume that u(t) = 0, that is, there is no input.

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• Set the initial conditions of the integrator

Block Parameters: Integrator1 🛛 🛛 🔀	Block Parameters: Integrator 🛛 🔀
- Integrator	_ Integrator
Continuous-time integration of the input signal.	Continuous-time integration of the input signal.
Parameters	Parameters
External reset: none	External reset: none
Initial condition source: internal	Initial condition source: internal
Initial condition:	Initial condition:
-2	2
Limit output	└── Limit output
Upper saturation limit:	Upper saturation limit:
inf	inf
Lower saturation limit:	Lower saturation limit:
inf	linf
Show saturation port	Show saturation port
Show state port	Show state port
Absolute tolerance:	Absolute tolerance:
auto	auto
Finable zero crossing detection	I ■ Enable zero crossing detection
OK Cancel <u>H</u> elp Apply	OK Cancel Help Apply

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